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# TEMPI: An Interposed MPI Library with a Canonical Representation of CUDA-aware Datatypes

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HPDC - Jun 24, 2021

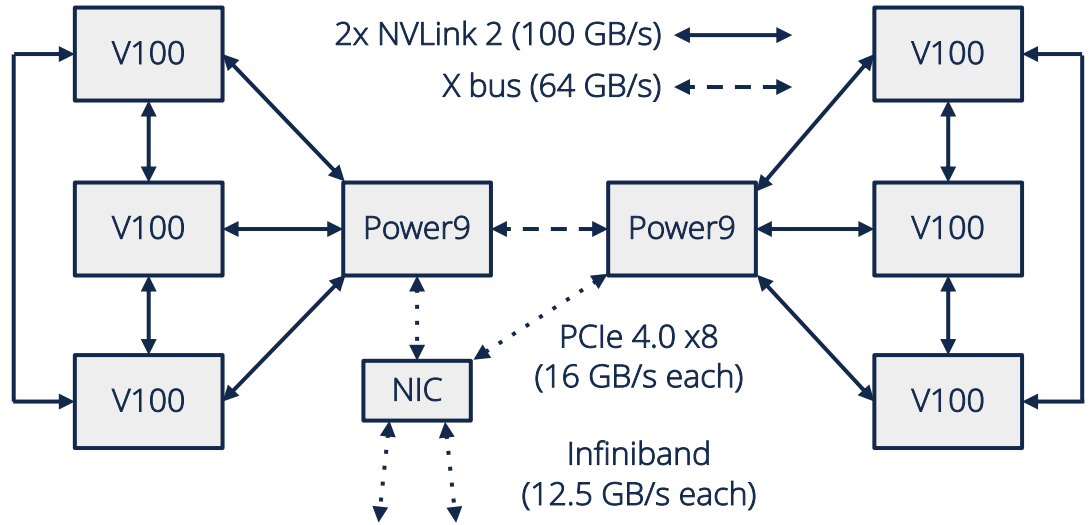
*Work completed at University of Illinois prior to joining Sandia National Labs*



## Outline

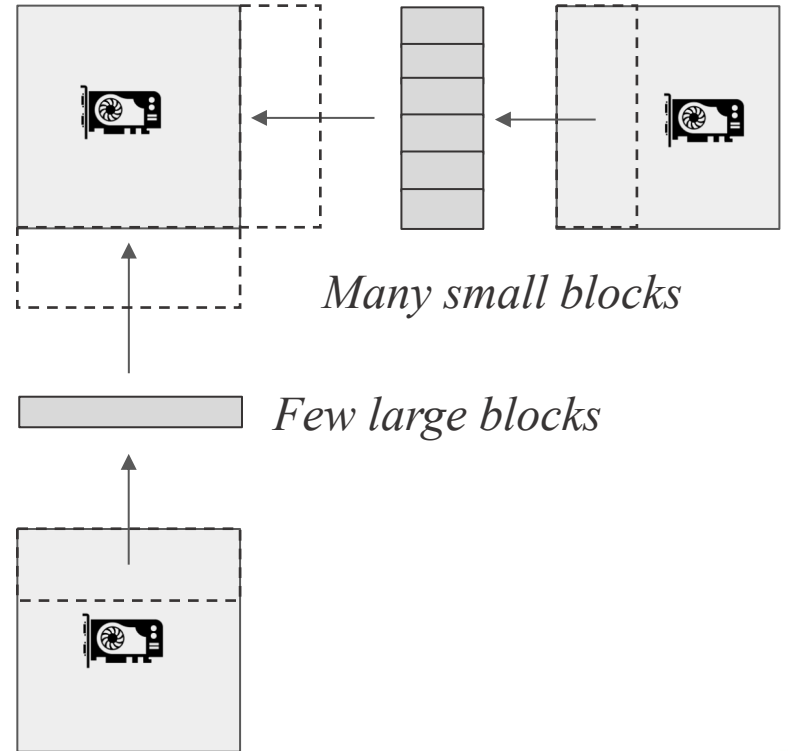
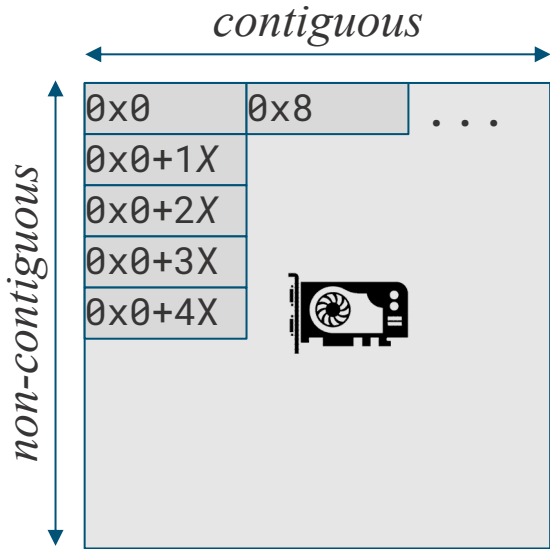
- Distributed GPU stencil, non-contiguous data
- Equivalence of strided datatypes and minimal representation
- GPU communication methods
- Deploying on managed systems
- Large messages and MPI datatypes
- Translation and canonicalization
- Automatic model-driven transfer method selection
- Interposed library implementation

# OLCF Summit Node

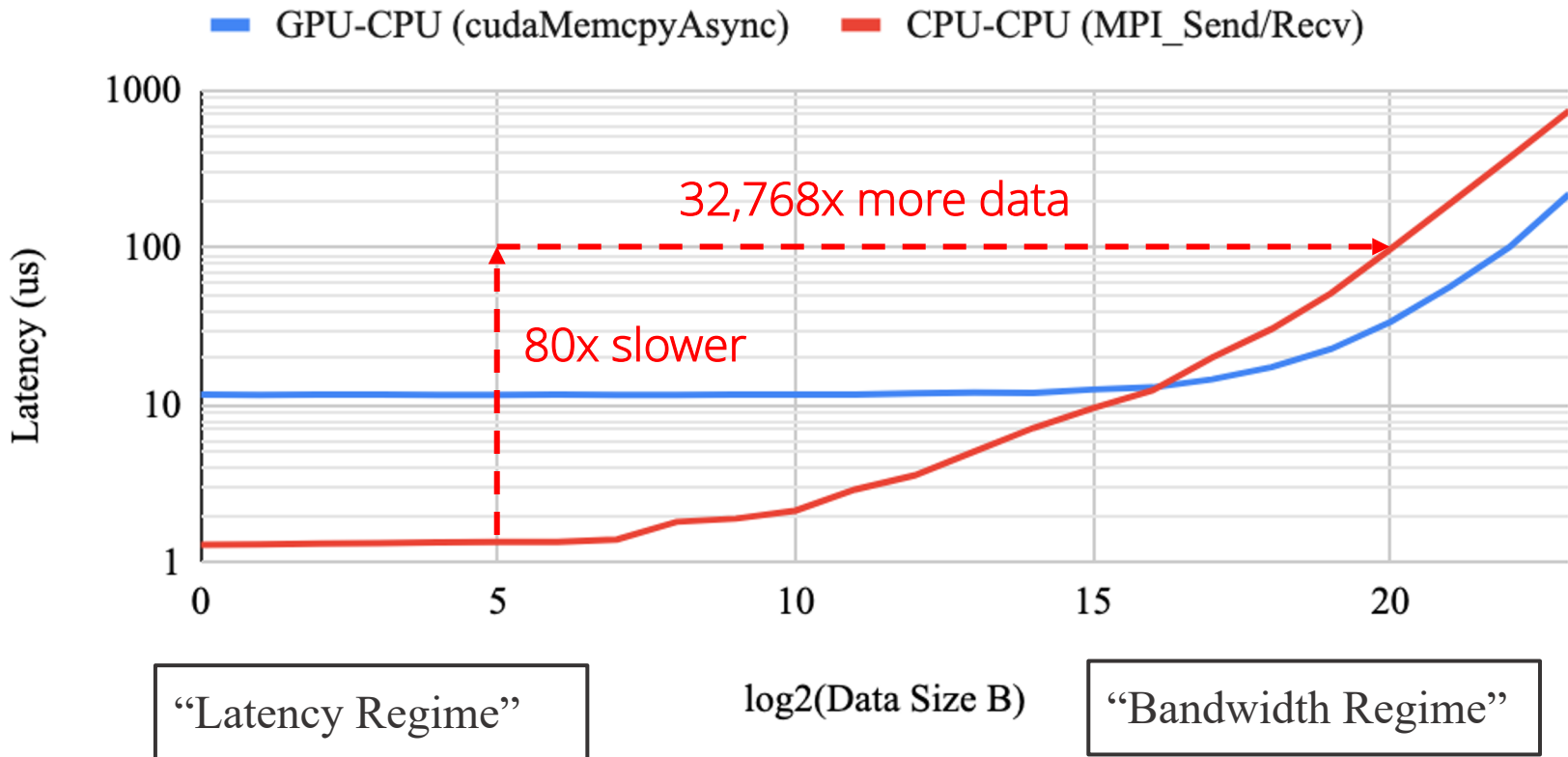


Summit Node  
(bidirectional bandwidth)

# Stencil Communication and non-contiguous Data



# OLCF Summit Latency vs Transfer Size



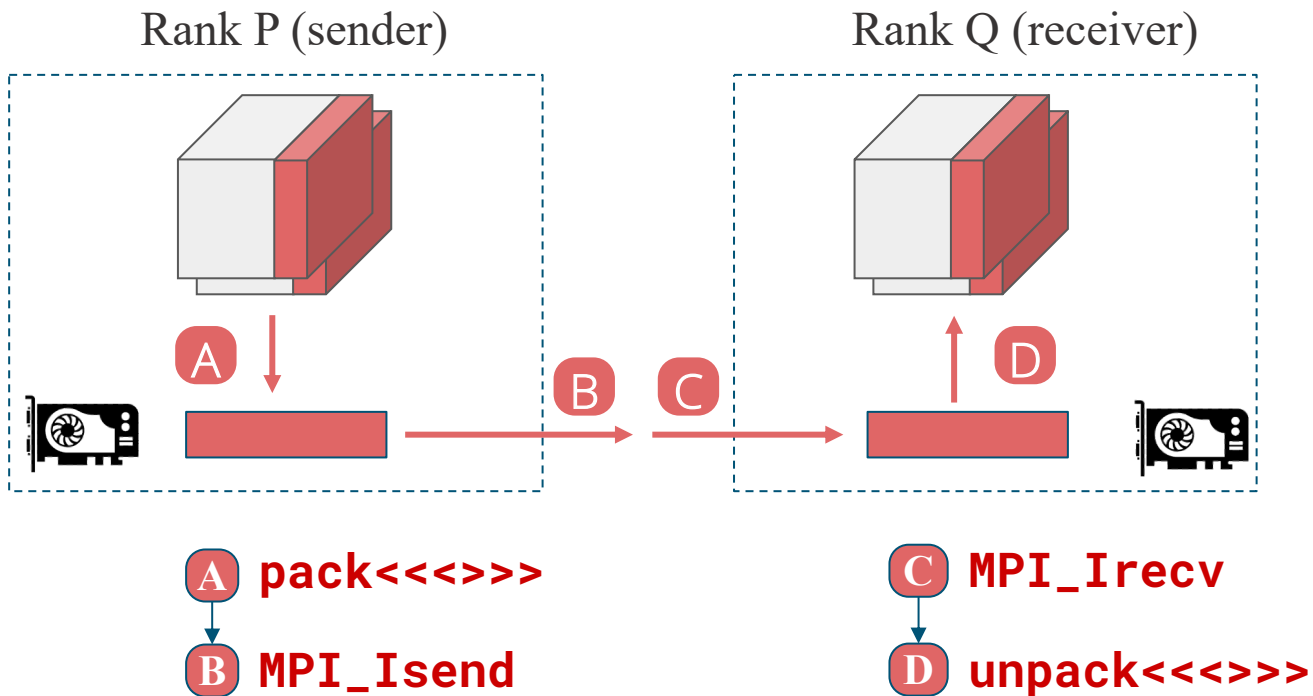
“Latency Regime”

log2(Data Size B)

“Bandwidth Regime”

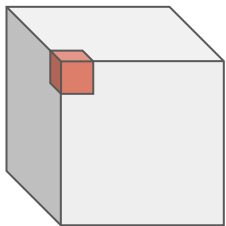


# CUDA-Aware MPI + Packing



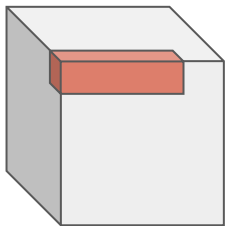
# MPI Derived Datatypes

"MPI\_Type\_contiguous(...)"



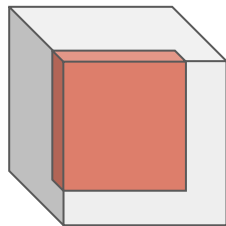
1 MPI\_BYTE

"MPI\_Type\_vector(...)"

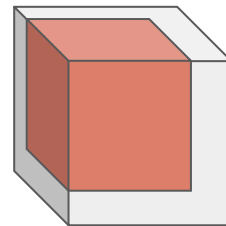


row of contiguous bytes

"MPI\_Type\_vector(...)"

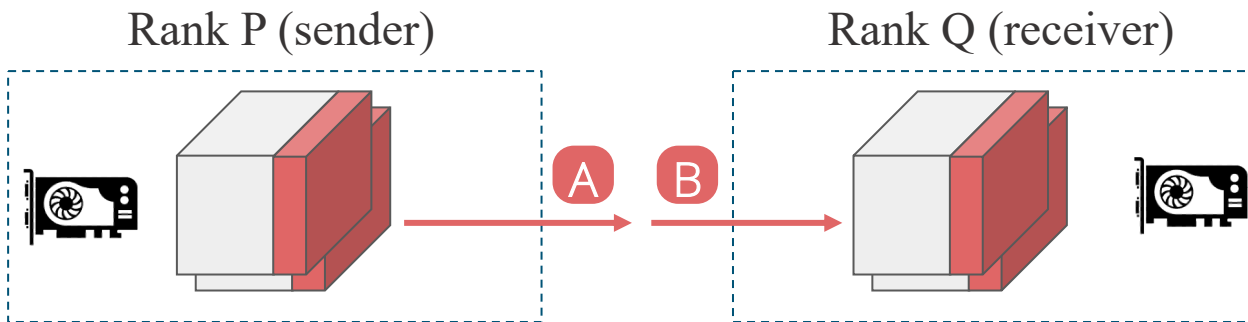


plane of non-contiguous rows



cuboid of non-contiguous planes

# CUDA-Aware MPI + MPI Derived Datatypes



**MPI\_Type...**

**MPI\_Type...**

**...**

**MPI\_Type\_commit**

**MPI\_Type...**

**MPI\_Type...**

**...**

**MPI\_Type\_commit**

*Setup (once):*

*Each halo exchange:*

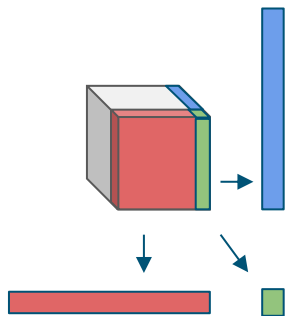
**A MPI\_Isend**

**B MPI\_Irecv**

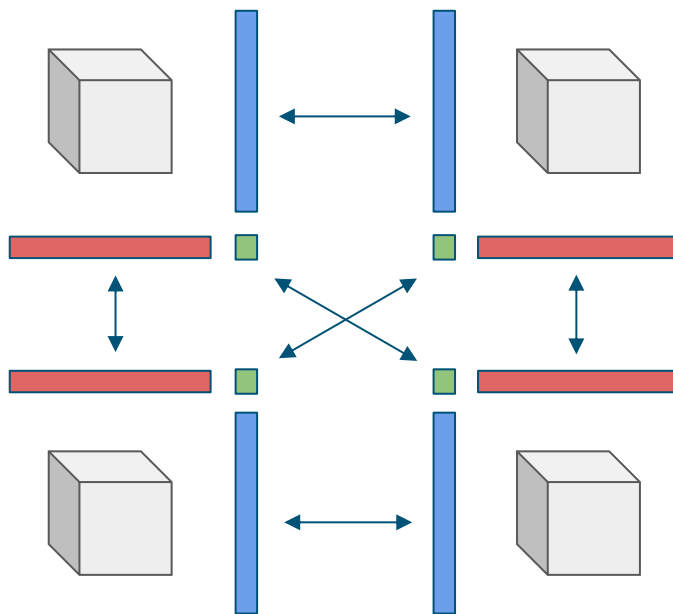




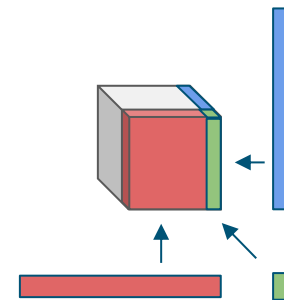
# "alltoallv" Halo Exchange



MPI\_Packs

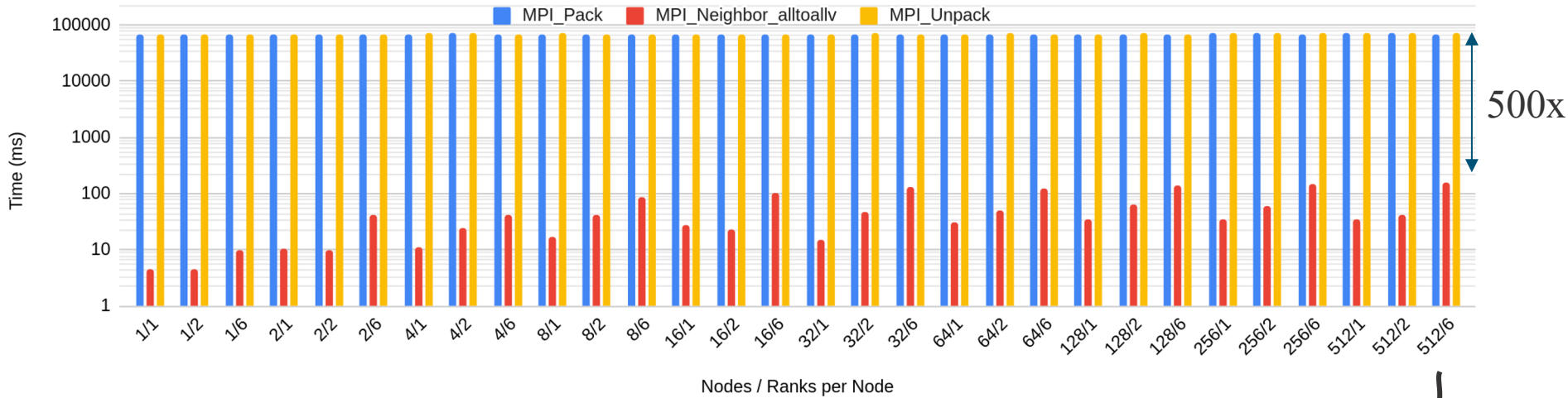


MPI\_Neighbor\_alltoallv



MPI\_Unpacks

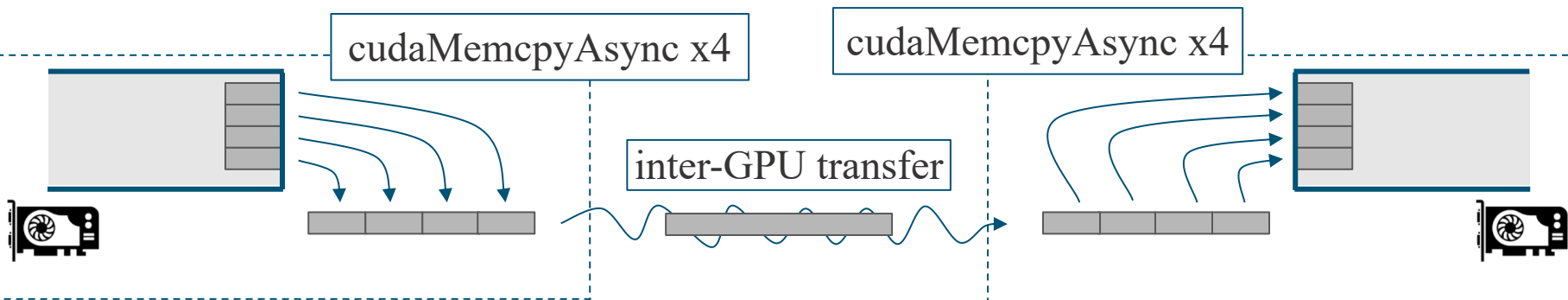
# “alltoallv” with MPI derived types



- MPI\_Neighbor\_alltoallv = ~500 MB/s/rank
- MPI\_Pack / MPI\_Unpack = ~1 MB/s



# MPI\_Send (Spectrum MPI)



“Latency Regime”



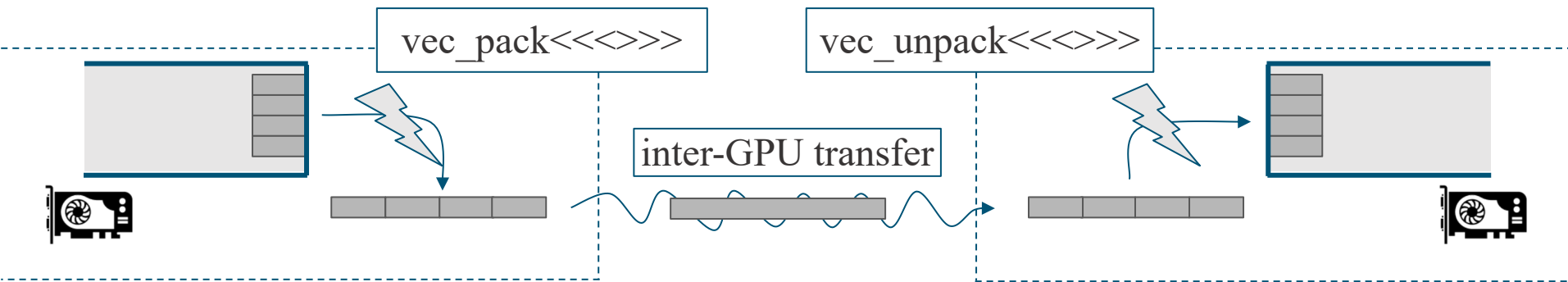
“Bandwidth Regime”



“Latency Regime”

# Better MPI\_Send (common foundation)

- GPU kernels to pack non-contiguous data



“Bandwidth Regime”

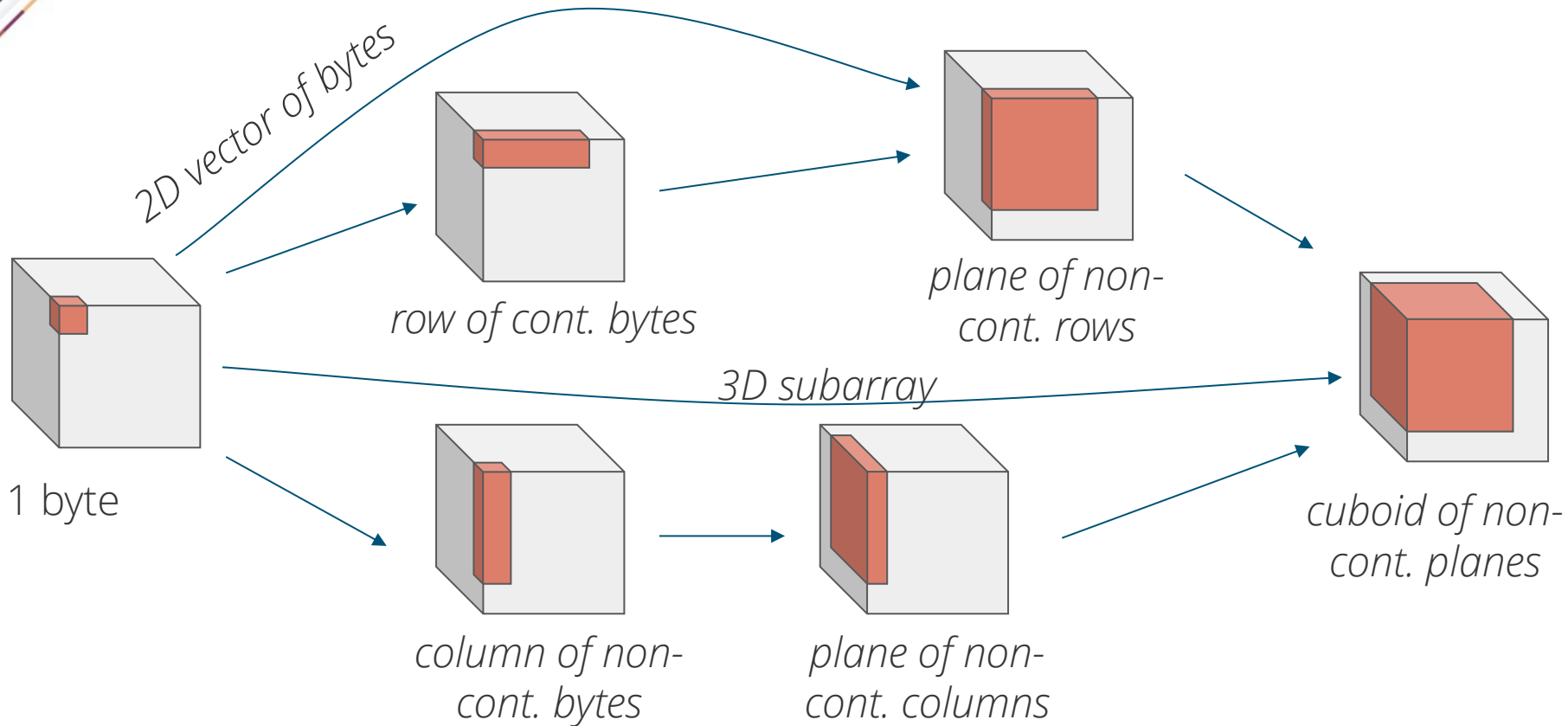


“Bandwidth Regime”



“Bandwidth Regime”

# MPI Derived Datatype Equivalence





MPI\_Type\_commit()



Translation  
*Convert MPI Derived Datatype into internal representation (IR)*



Canonicalization  
*Convert semantically-equivalent IR to simplified form*



Kernel Selection  
*Choose packing/unpacking kernel for future operations*

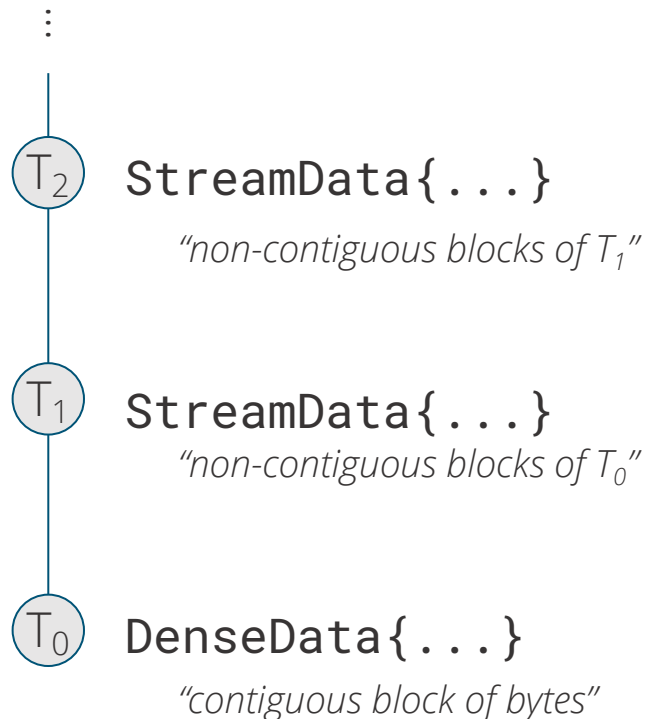


## IR - “Internal Representation”

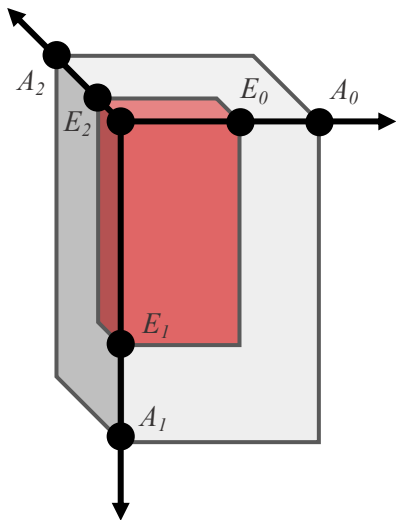
```
StreamData {  
    integer offset; // offset (B) of the first element  
    integer stride; // pitch (B) between element  
    integer count; // number of elements  
}
```

```
DenseData {  
    integer offset; // offset (B) of the first byte  
    integer extent; // number of bytes  
}
```

Hierarchy of StreamData, rooted at DenseData



# Example



| Type     |   |   |  |
|----------|---|---|--|
| cuboid   | ○ | StreamData{offset:0, count: $E_2$ , stride: $A_1 * A_0$ } |  |
|          | ○ | StreamData{offset:0, count:1, stride: $E_1 * A_0$ }       |  |
| plane    | ○ | StreamData{offset:0, count: $E_1$ , stride: $A_0$ }       |  |
|          | ○ | StreamData{offset:0, count:1, stride: $E_0$ }             |  |
| row      | ○ | StreamData{offset:0, count: $E_0$ , stride:1}             |  |
|          | ○ | StreamData{offset:0, count:1, stride:1}                   |  |
| MPI_BYTE | ○ | DenseData{offset:0, extent: 1}                            |  |





## TEMPI Datatype Handling

### Translation

*Convert MPI Derived Datatype into internal representation (IR)*



### Canonicalization

*Convert semantically-equivalent IR to simplified form*

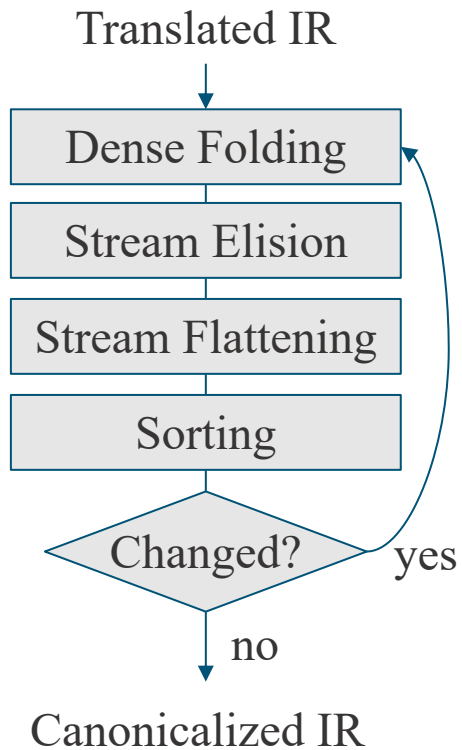


### Kernel Selection

*Choose packing/unpacking kernel for IR*



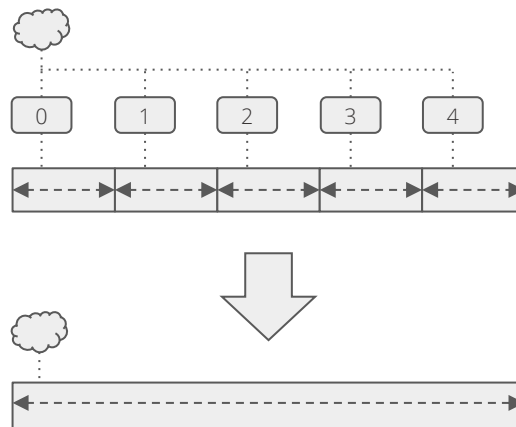
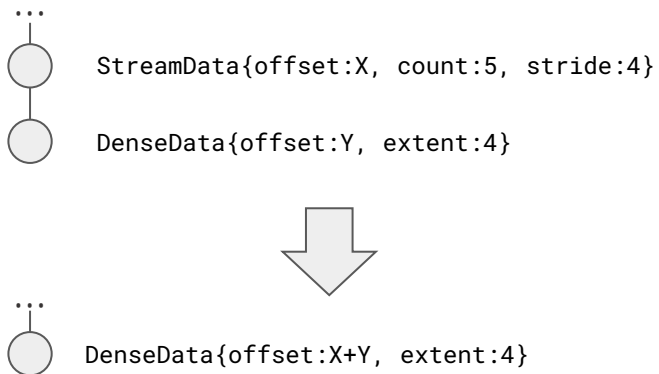
## Canonicalization





## Canonicalization: Dense Folding

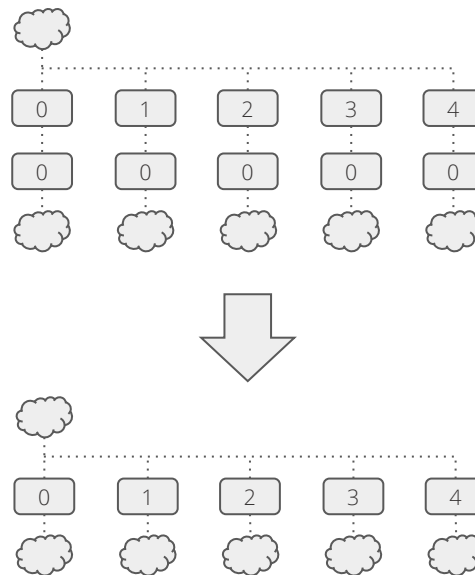
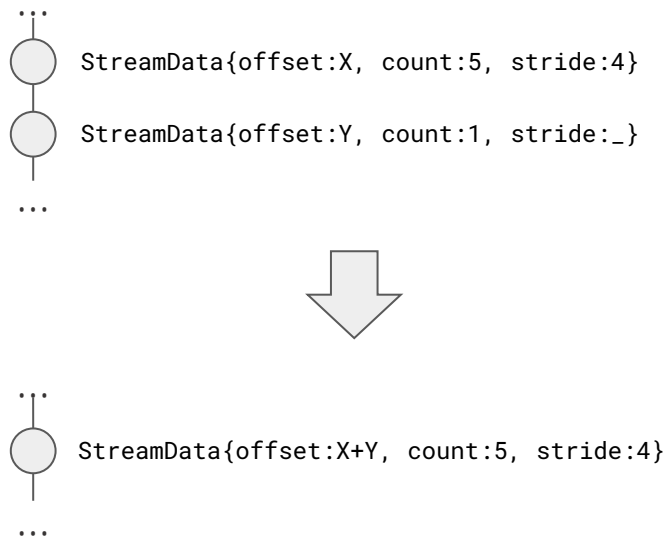
- `StreamData` is contiguous `DenseData` (parent of MPI named type)





## Canonicalization: Stream Elision

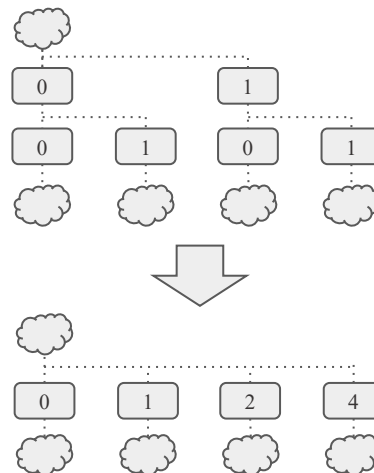
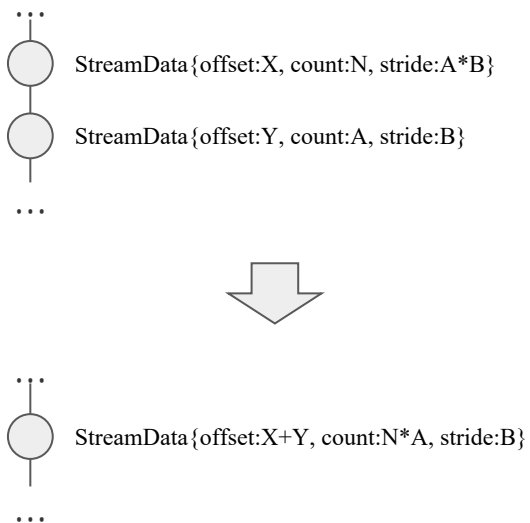
- Remove `StreamData` with `count = 1` (MPI Vector blocks commonly have one element)





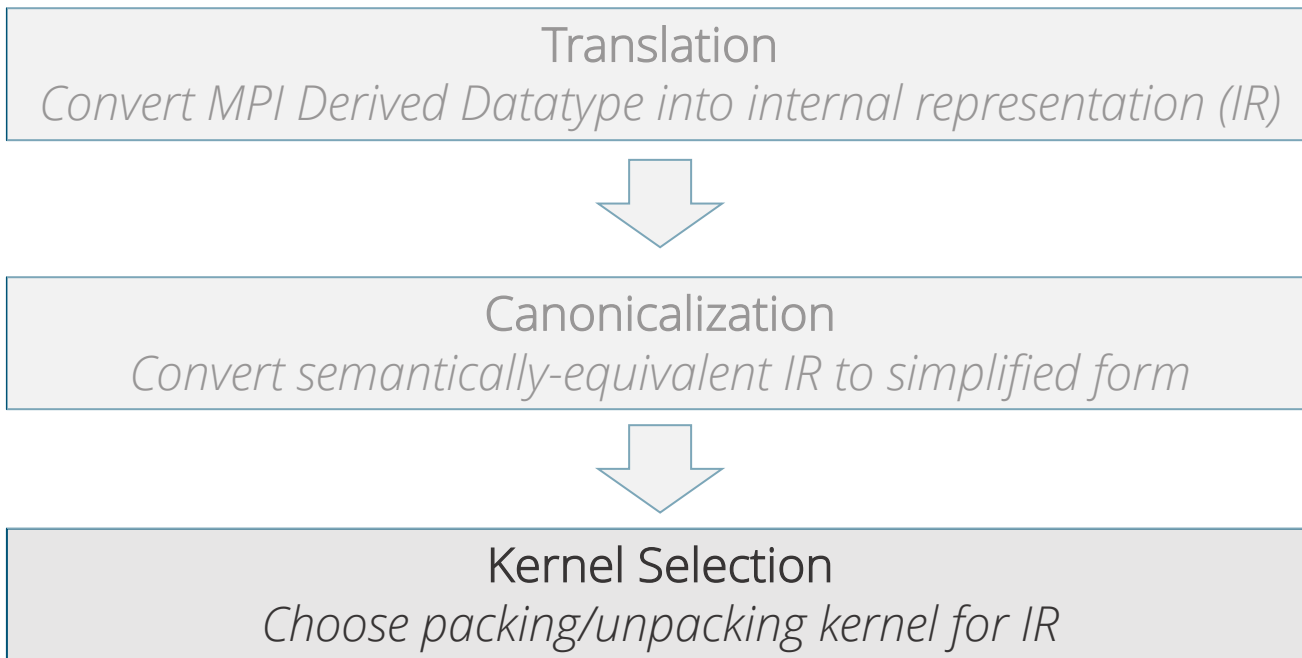
## Canonicalization: Stream Flattening

- e.g. two vectors of three vs. one vector of six

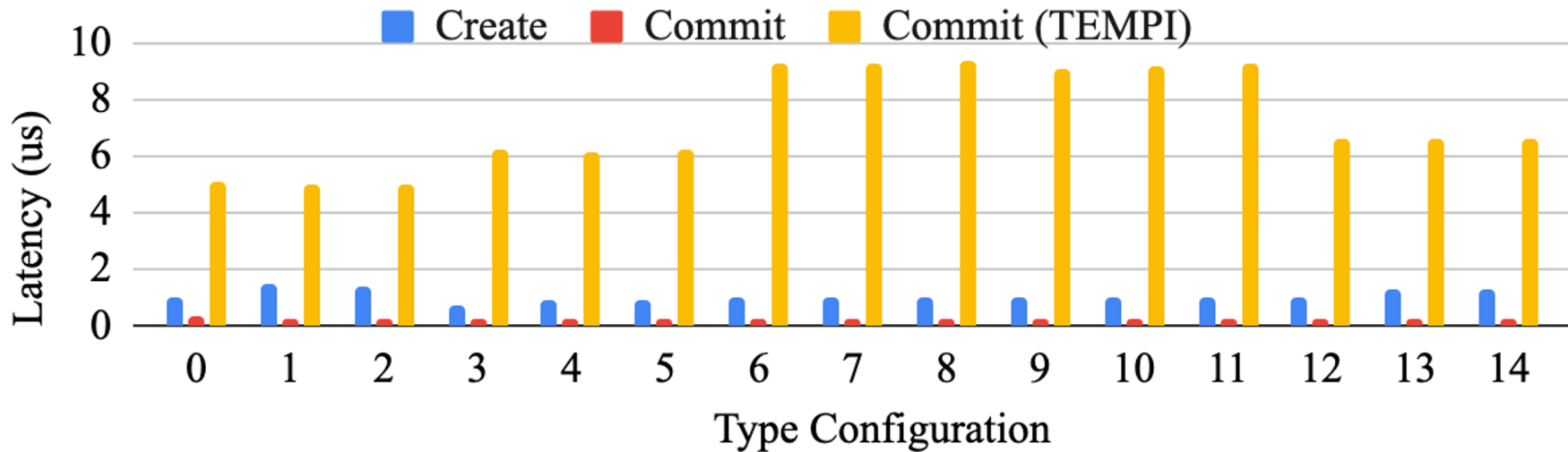




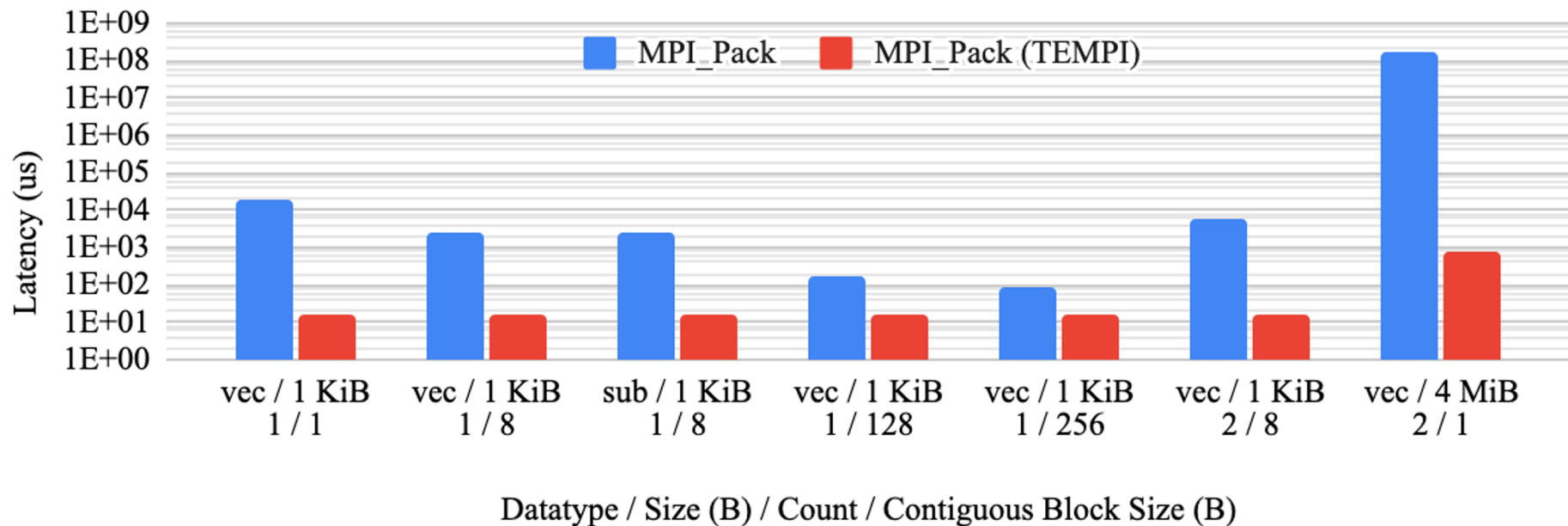
## TEMPI Datatype Handling



# MPI\_Type\_commit Time



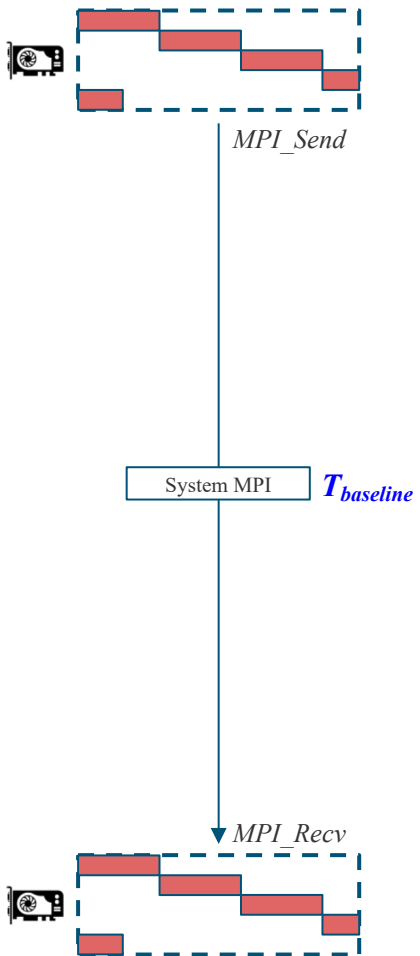
## MPI\_Pack Results





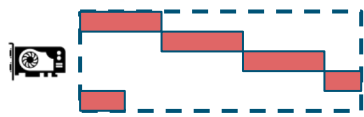


# CUDA-Aware System MPI





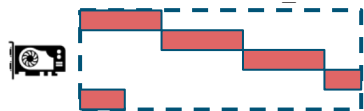
# CUDA-Aware System MPI



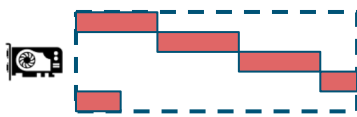
*MPI\_Send*

System MPI  $T_{baseline}$

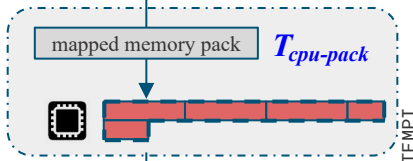
*MPI\_Recv*



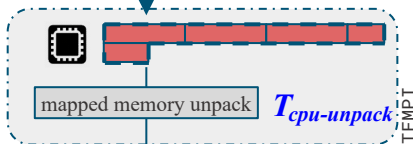
# TEMPI "One-shot"



*MPI\_Send*



System MPI  $T_{cpu-cpu}$



*MPI\_Recv*





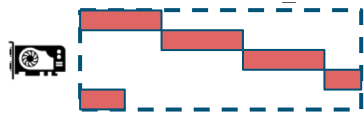
# CUDA-Aware System MPI



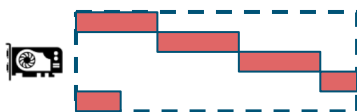
*MPI\_Send*

System MPI  $T_{baseline}$

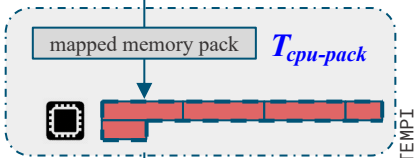
*MPI\_Recv*



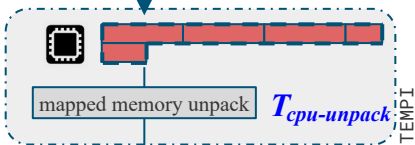
# TEMPI "One-shot"



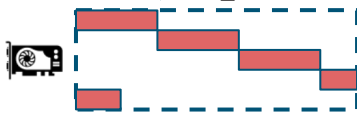
*MPI\_Send*



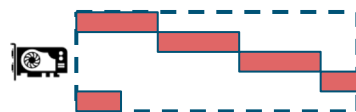
System MPI  $T_{cpu-cpu}$



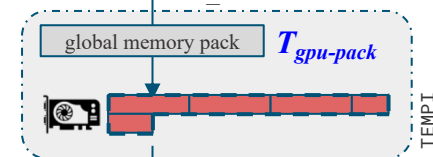
*MPI\_Recv*



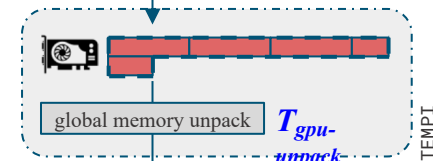
# TEMPI "Device"



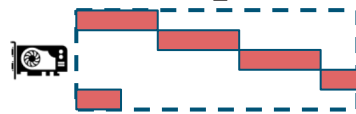
*MPI\_Send*



System MPI  $T_{gpu-gpu}$



*MPI\_Recv*





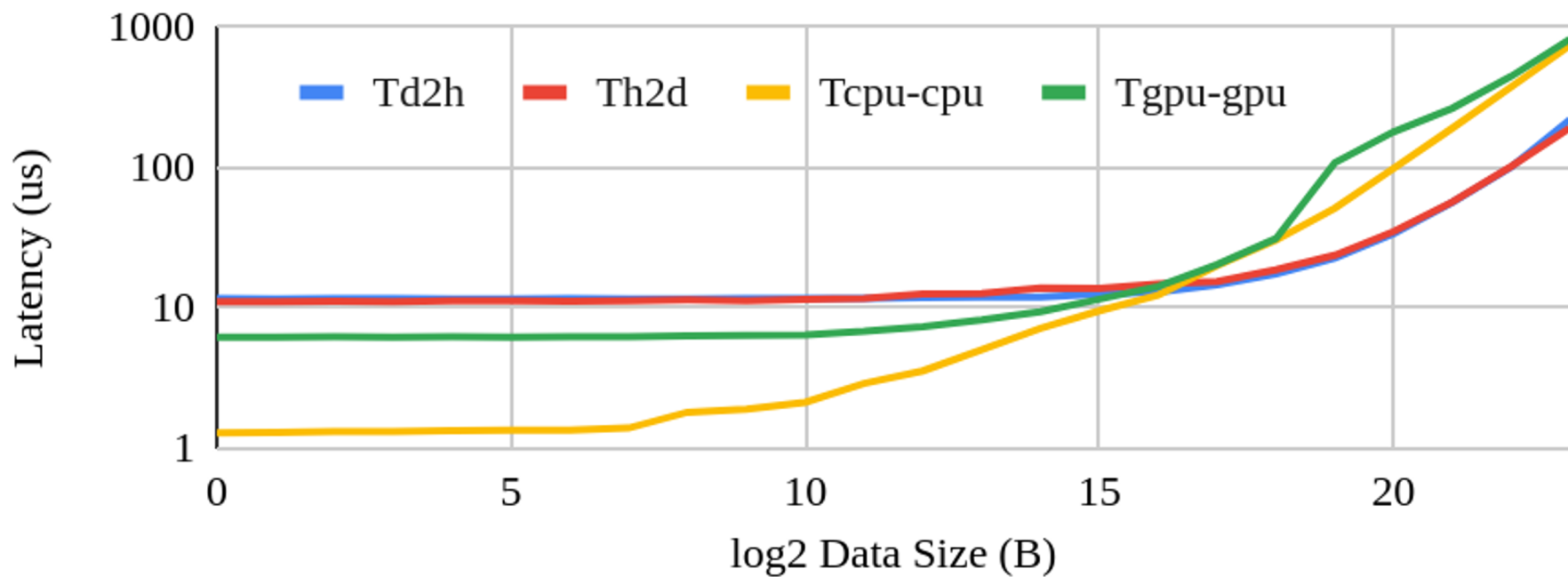
## Performance Modeling

$$T_{device} = T_{gpu-pack} + T_{gpu-gpu} + T_{gpu-unpack}$$

$$T_{oneshot} = T_{host-pack} + T_{cpu-cpu} + T_{host-unpack}$$

$$T_{staged} = T_{gpu-pack} + T_{d2h} + T_{cpu-cpu} + T_{h2d} + T_{gpu-unpack}$$

## Contiguous Transfer Measurements



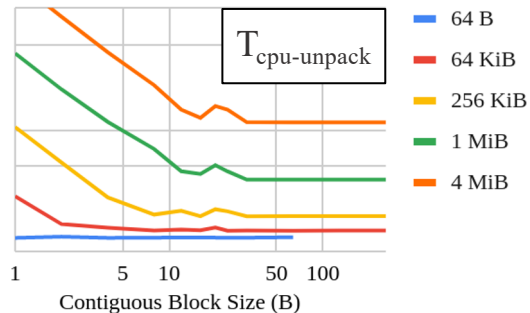
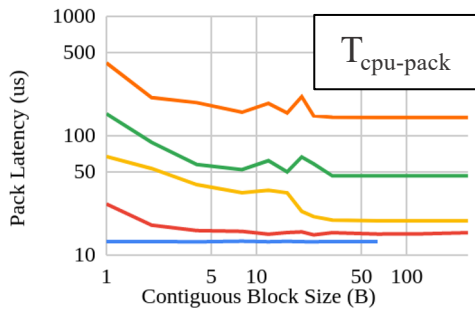
*T depends on # bytes transferred*

# One-shot and Device Pack and Unpack

ONE-SHOT

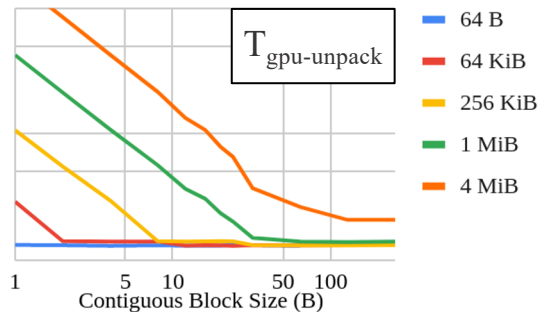
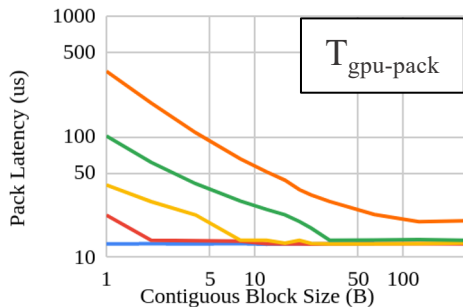
PACK

UNPACK



- 64 B
- 64 KiB
- 256 KiB
- 1 MiB
- 4 MiB

DEVICE

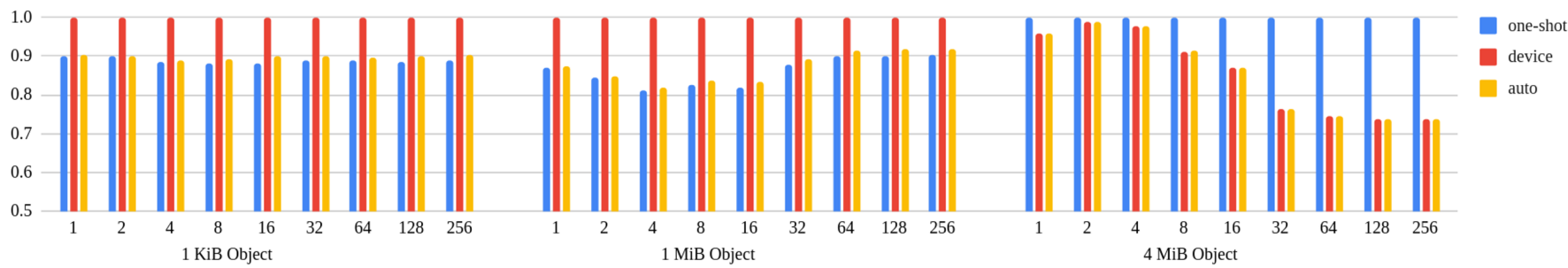


- 64 B
- 64 KiB
- 256 KiB
- 1 MiB
- 4 MiB

*T depends on object size and block size*

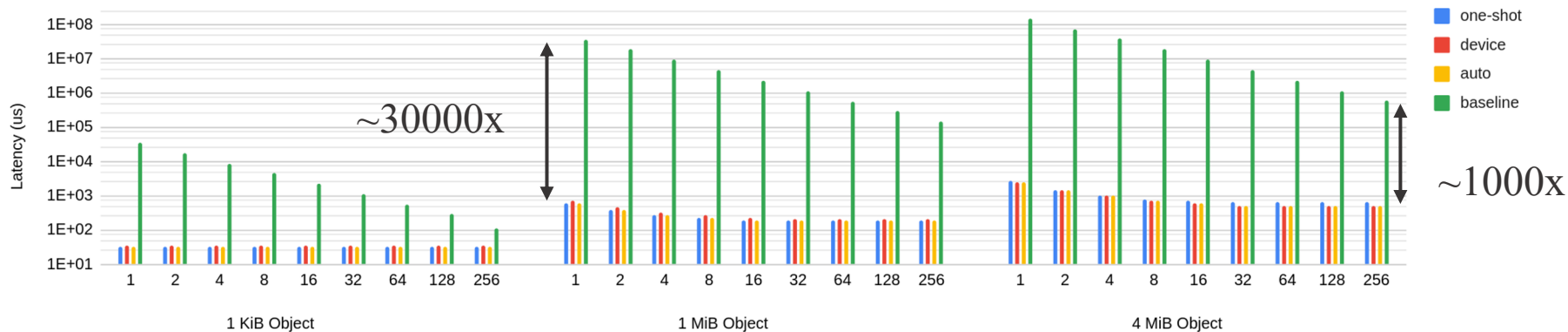
# MPI\_Send Microbenchmark

Normalized Latency



*Minimal runtime performance-modeling overhead  
Performance model reliably chooses faster method*

## MPI\_Send/Recv Latency for 2D objects with different block sizes

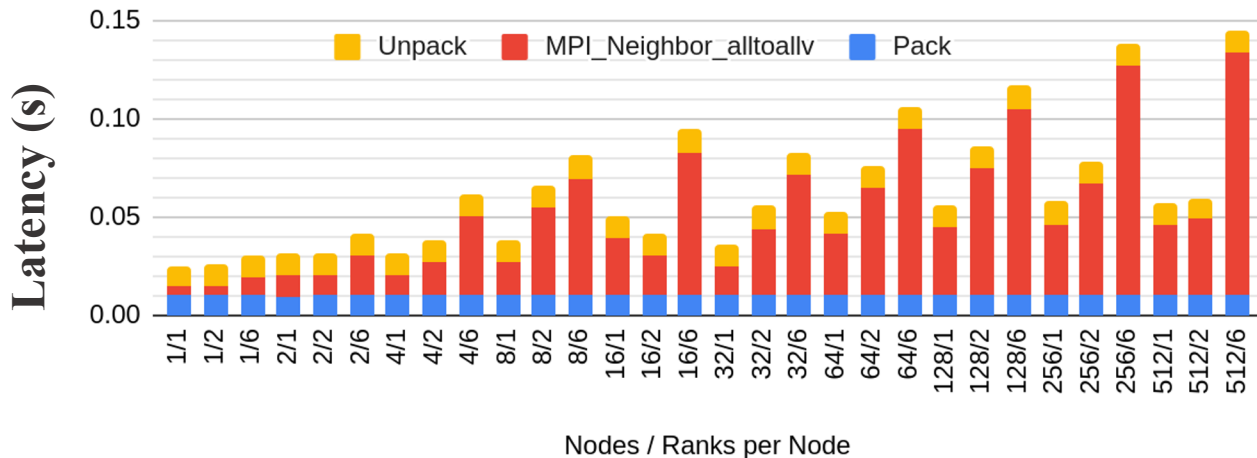


*Large latency improvement from datatype handling*  
*Small additional improvement from automatic method selection*

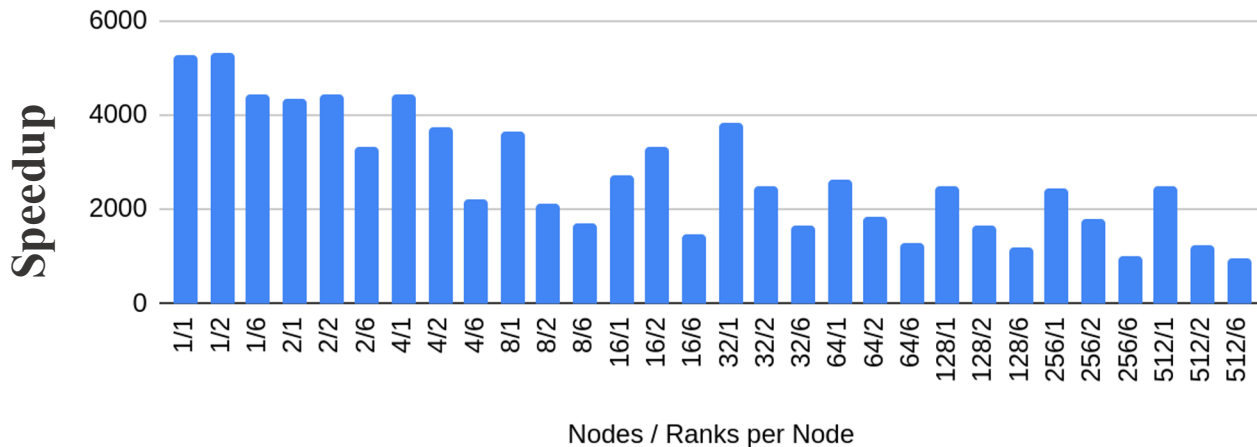


# Halo Exchange

*With TEMPI, non-contiguous packing no longer dominates*



*Large speedup in 3D halo exchange*



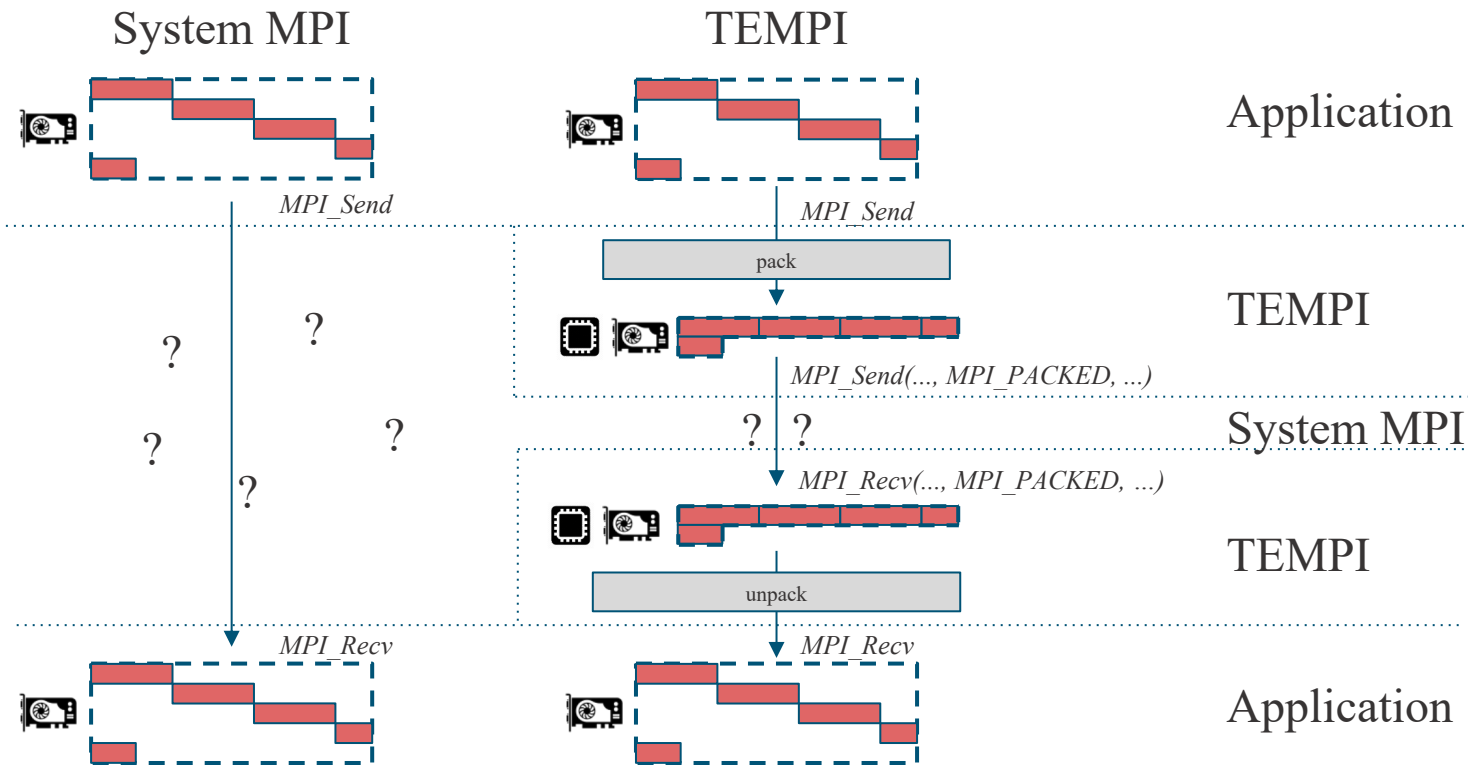


## A Practical Challenge: Deploying MPI experiments on a Supercomputer

- Large-scale systems are tightly controlled
  - Can't just make whatever changes you want
- Usually one MPI (or maybe two) are deployed on the system
  - Rarely bugfixed (if ever)
  - Even more rarely are new features added
- Difficult or impossible to make experimental modifications
  
- MPI has a well-defined standard
  - Take advantage of this + how OS loads libraries to inject modifications



# TEMPI's Architecture: Interposer Library



app.c

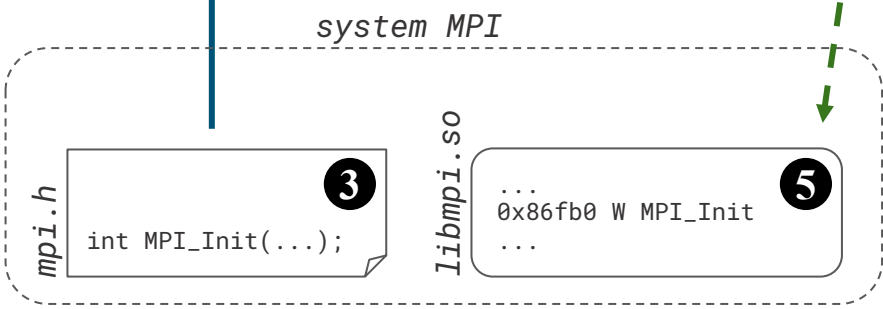
```
#include <mpi.h> 1  
  
int main(int argc, char **argv) {  
    MPI_Init(&argc, &argv);  
}
```



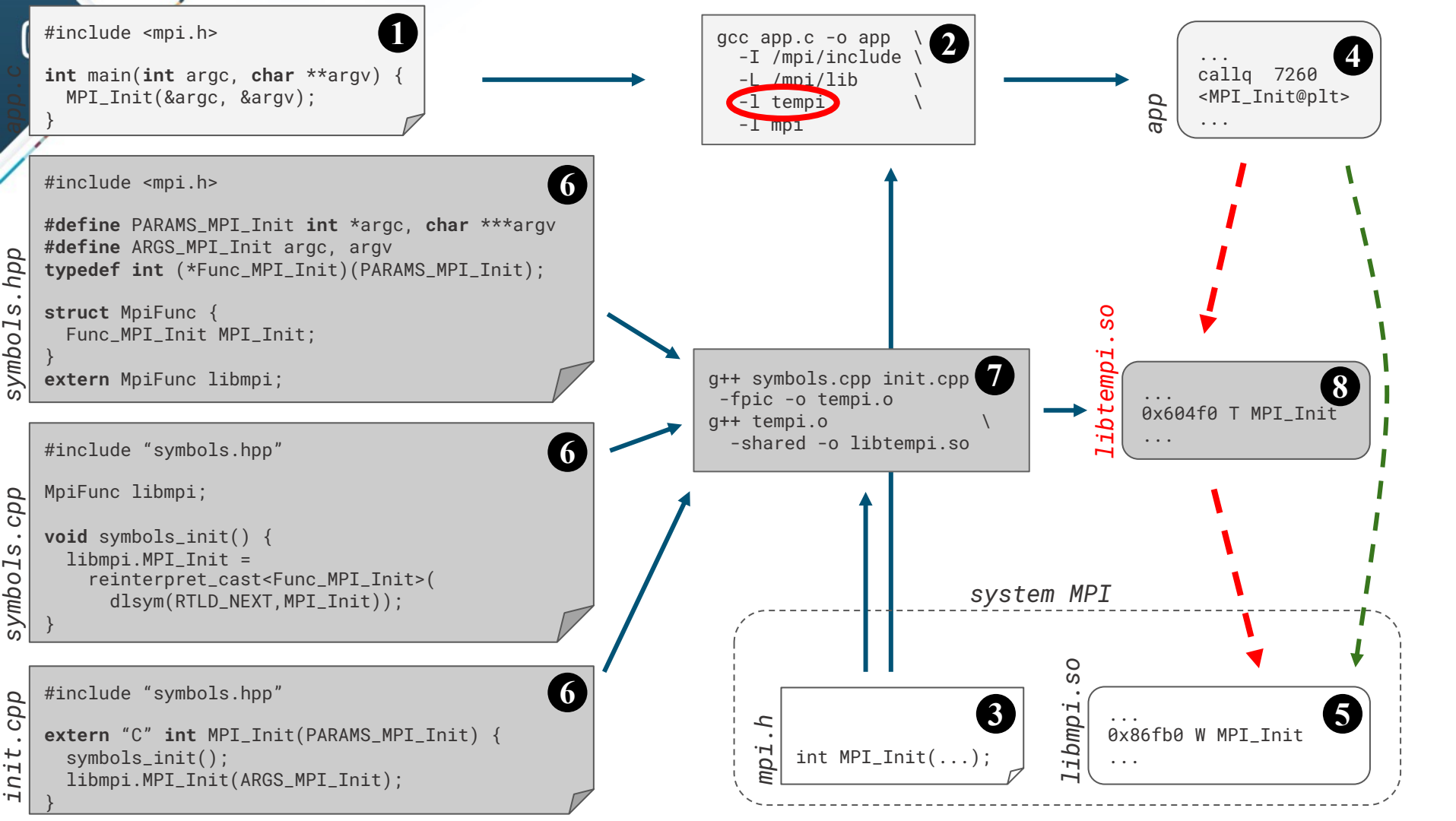
```
gcc app.c -o app \  
-I /mpi/include \  
-L /mpi/lib \  
-l mpi 2
```



```
...  
callq 7260 4  
<MPI_Init@plt>  
...
```



**8**





## Conclusions & Future Work

- Canonicalization approach works
  - 👍 Speedup for unmodified applications on OLCF summit
  - 👍 Any strided datatype
- Simple performance model to select GPU data transfer method
  - 👍 speedup
  - 👎 < 2x speedup
- Interposed library approach nice for experiments & prototype deployment
  - 👍 Easy to use without system privileges
  - 👎 Limited integration with existing MPI
- OpenMPI, MPICH, MVAPICH have other strategies
  - Use if available - covers some or all of the same problems
  - Comparison of MPI datatype performance would be useful to community
- [github.com/cwpearson/tempi](https://github.com/cwpearson/tempi)



## Acknowledgements

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Thank you

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[github.com/cwpearson/tempi](https://github.com/cwpearson/tempi)

This work was completed prior to joining Sandia National Labs.